



بعض الطرائق العددية المتقدمة في الفروغ المتشعبة :

### ① طريقة Lax-Friedrichs (LFM)

نقطة لسيا المعادلة التفاضلية :  $u_t + a u_x = 0$  ✓

نطبق الفروغ التكرارية بالنسبة للزمن والمكان بالنسبة للسرعة :

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = -a \frac{u_{i+1}^n - u_{i-1}^n}{2h}$$

$$u_i^{n+1} - u_i^n = -\frac{a \Delta t}{2h} [u_{i+1}^n - u_{i-1}^n]$$

$$u_i^{n+1} = \frac{u_{i-1}^n + u_{i+1}^n}{2} + \dots$$

$$u_i^{n+1} = \frac{1}{2} [u_{i-1}^n + u_{i+1}^n] + a \left( \frac{\Delta t}{2h} \right) [u_i^n - u_i^n]$$

فصل مع معادلات الفروغ المتشعبة

### ② طريقة Up Wind

نأخذ الطريقة التراجعية للزمن و التقدمية للزمن :

فصل مع المعادلات :

$$u_i^{n+1} = u_i^n - a \frac{\Delta t}{h} (u_i^n - u_{i-1}^n)$$

(1)

طريقة (Beam-Warming)

$$U_i^{j+1} = U_i^j - \alpha \frac{\Delta t}{2h} (3U_i^j - 4U_{i-1}^j + U_{i-2}^j) \\ + \frac{(\alpha \Delta t)^2}{2(h)^2} (U_i^j - 2U_{i-1}^j + U_{i-2}^j)$$

⋮

### 3.6.2 Summary

In what follow I summarize the most salient aspects of the different finite-difference operators discussed so far and report, for each of them, the truncation error  $\epsilon_T$ , the amplification factor  $|\lambda|^2$  and the finite-difference representation of the advection equation 3.2.

$$u_t = c u_x$$

Method	$\epsilon_T$	$ \lambda ^2$ for $(k\Delta x \ll 1)$	finite-difference form
Upwind	$O(\Delta t, \Delta x)$	$1 - 2 \alpha (1 -  \alpha )\cos(k\Delta x)$	$u_j^{n+1} = u_j^n \mp \alpha(u_{j\pm 1}^n - u_j^n)$
FTCS	$O(\Delta t, \Delta x^2)$	$1 + \sin^2(k\Delta x)\alpha^2$	$u_j^{n+1} = u_j^n - \alpha(u_{j+1}^n - u_{j-1}^n)$
Lax Friedrichs	$O(\Delta t, \Delta x^2)$	$1 - \sin^2(k\Delta x)(1 - \alpha^2)$	$u_j^{n+1} = \frac{1}{2}(u_{j+1}^n + u_{j-1}^n) - \alpha(u_{j+1}^n - u_{j-1}^n)$
Lepafrog	$O(\Delta t^2, \Delta x^2)$	1	$u_j^{n+1} = u_j^{n-1} - \alpha(u_{j+1}^n - u_{j-1}^n)$
Lax Wendroff	$O(\Delta t^2, \Delta x^2)$	$1 - \alpha^2(1 - \alpha^2)\sin^2(k\Delta x)$	$u_j^{n+1} = u_j^n - \frac{1}{2}\alpha(u_{j+1}^n - u_{j-1}^n) - \frac{1}{2}\alpha^2(u_{j+1}^n - 2u_j^n + u_{j-1}^n)$

Table(3.): Schematic summary of the finite-difference operators discussed so far.

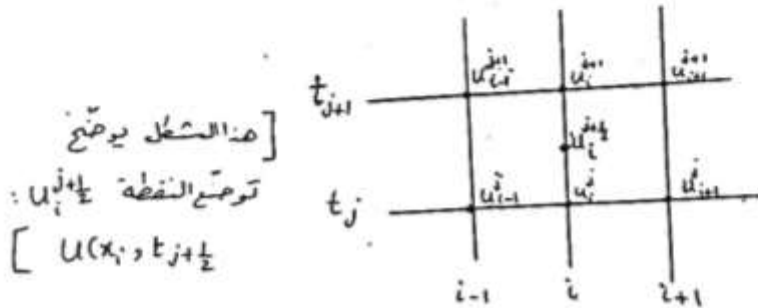
(3)

خطأ الاقتران بطريقة تانتا : Truncation Error of  $\theta$ -method

لكنه لدينا المعادلة من الشكل  $u_t = u_{xx}$   
 مركزية  $\theta$  تقدمية

$$(*) \quad \frac{u_i^{j+1} - u_i^j}{k} = \theta \underbrace{\left[ \frac{u_{i-1}^{j+1} - 2u_i^{j+1} + u_{i+1}^{j+1}}{h^2} \right]}_A + (1-\theta) \underbrace{\left[ \frac{u_{i-1}^j - 2u_i^j + u_{i+1}^j}{h^2} \right]}_B$$

نوسخ الحدود في خطأ الاقتران ليتمثل  $u(x_i, t_{j+\frac{1}{2}})$



بالتسلسل الجورجيه :

$$u_i^{j+\frac{1}{2}} = \left[ u - \frac{1}{2}k u_t + \frac{1}{2} \left( \frac{1}{2}k \right)^2 u_{tt} + \frac{1}{3!} \left( \frac{1}{2}k \right)^3 u_{ttt} + \dots \right]_i$$

$$u_i^j = \left[ u - \left( \frac{1}{2}k \right) u_t + \frac{1}{2} \left( \frac{1}{2}k \right)^2 u_{tt} - \frac{1}{3!} \left( \frac{1}{2}k \right)^3 u_{ttt} + \dots \right]_i$$

$$\Rightarrow \frac{u_i^{j+1} - u_i^j}{k} = \left[ u_t + \frac{1}{24} k^2 u_{ttt} + \dots \right]_i$$

وهذا هو الطرف الايسر من العلاقة \*

(4)

مأنيضا نخذ نعلم :

$$A = \frac{u_{i+1}^{j+1} - 2u_i^{j+1} + u_{i-1}^{j+1}}{h^2} = \left[ u_{xx} + \frac{1}{12} h^2 u_{xxxx} + \dots \right]_i^{j+1}$$

$$B = \frac{u_{i+1}^j - 2u_i^j + u_{i-1}^j}{h^2} = \left[ u_{xx} + \frac{1}{12} h^2 u_{xxxx} + \dots \right]_i^j$$

لنؤسس الحدود من الطرف الأيمن لتصل انقطاع  $u_i^{j+1}$   
 وذلك بالشرح التالي - لكل حد من حدود الطرف الأيمن  $(u_{xxxx}, u_{xx})$

$$\Rightarrow A = \left[ u_{xx} + \left(\frac{K}{2}\right) u_{xxt} + \frac{1}{2} \left(\frac{K}{2}\right)^2 u_{xxtt} + \dots \right]_i^{j+\frac{1}{2}}$$

$$+ \frac{1}{12} h^2 \left[ u_{xxxx} + \left(\frac{K}{2}\right) u_{xxxxt} + \dots \right]_i^{j+\frac{1}{2}}$$

مأنيضا  $\Rightarrow$

$$B = \left[ u_{xx} - \left(\frac{K}{2}\right) u_{xxt} + \frac{1}{2} \left(\frac{K}{2}\right)^2 u_{xxtt} + \dots \right]_i^{j+\frac{1}{2}}$$

$$+ \frac{1}{12} h^2 \left[ u_{xxxx} - \left(\frac{K}{2}\right) u_{xxxxt} + \dots \right]_i^{j+\frac{1}{2}}$$

$$\theta A + (1-\theta) B = [\theta + 1 - \theta] \left[ u_{xx} + \frac{K^2}{8} u_{xxtt} + \frac{1}{12} h^2 u_{xxxx} \right]_i^{j+\frac{1}{2}}$$

$$+ [\theta - 1 + \theta] \left[ \frac{K}{2} u_{xxt} + \frac{1}{2} \left(\frac{K}{2}\right)^2 u_{xxtt} + \dots \right]_i^{j+\frac{1}{2}}$$

$$= \left[ u_{xx} + \frac{K^2}{8} u_{xxtt} + \frac{1}{12} h^2 u_{xxxx} + \dots \right. \\ \left. + (2\theta - 1) \frac{K}{2} \left( u_{xxt} + \frac{1}{12} h^2 u_{xxxxt} + \dots \right) \right]_i^{j+\frac{1}{2}}$$

وهذا هو الطرف الأيمن من العلاقة \*

وبما أن  $u_{xx} - u_t = 0$  نجد أن :

$$T_i^{j+\frac{1}{2}} = \frac{1}{2}(1-2\theta) \cdot K u_{xxt} - \frac{1}{12} h^2 u_{xxxx} + K^2 \left[ \frac{1}{24} u_{ttt} + \frac{1}{8} u_{xxtt} \right] + \dots$$

وبما أن  $u_{xx} = u_t$  و  $u_{xxx} = u_{xt}$  تصبح العبارة :

$$T_i^{j+\frac{1}{2}} = \frac{1}{2}(1-2\theta) K u_{xxt} - \frac{1}{12} h^2 u_{xxxx} + \frac{K^2}{12} u_{xxxxx} + \dots$$

في الحالة الخاصة  $\theta = \frac{1}{2}$  يصبح الحد الأول صفراً

وتكون خطأ رتبة ثالثة بالنسبة للمرضوع والزمن  $O(h^2, \Delta t^2)$

و هذه تدعى طريقة كرانك نيكلسون .

### The Leapfrog Method

الفكرة في هذه الطريقة أننا نزيد من الدقة (النسبة للزمن  $\Delta t$ ) باستخدام الفروقات المركزية .

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$$

← مركزية
→ مركزية

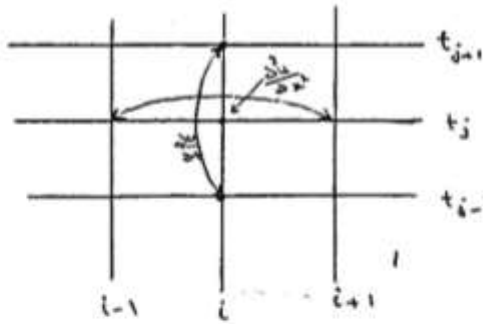
$$\frac{u_i^{j+1} - u_i^{j-1}}{2\Delta t} = \frac{u_{i+1}^j - 2u_i^j + u_{i-1}^j}{h^2}$$

①  $u_i^{j+1} = u_i^{j-1} + 2r(u_{i+1}^j - 2u_i^j + u_{i-1}^j)$

تصبح العبارة :

$$r = \frac{K}{h^2}$$

وسهولة يمكن أن نجد :  $T_i^j \sim O(K^2, h^2)$



إذا نظرنا إلى صيغة فورييه (نيومان)  $u_i \sim \frac{1}{\lambda} e^{ikl}$

$$\lambda = \frac{1}{\lambda} + 2r(e^{ikh} - 2 + e^{-ikh}) \leftarrow \text{تصبح المعادلة ①}$$

$$\lambda = \frac{1}{\lambda} + 2r(\cos(kh) - 2) \quad \left[ \cos x = \frac{e^{ix} + e^{-ix}}{2} \right]$$

$$\lambda = \frac{1}{\lambda} - 8r \underbrace{\sin^2 \frac{kh}{2}}_P \quad \left[ \sin^2 \frac{x}{2} = \frac{1 - \cos x}{2} \right]$$

نسعى  $(P = \sin^2 \frac{kh}{2})$

$$\Rightarrow \lambda^2 + 8rp\lambda - 1 = 0$$

نجد  $0 \leq P \leq 1$

بجمل المعادلتين:

$$\Delta = (8rp)^2 + 4$$

$$= 4(16r^2p^2 + 1)$$

$$\Rightarrow \lambda_{1,2} = -4rp \pm \sqrt{16r^2p^2 + 1}$$

$$\lambda_1 = \sqrt{16r^2p^2 + 1} - 4rp < 1$$

$$\lambda_2 = -\sqrt{16r^2p^2 + 1} - 4rp < -1 \Rightarrow |\lambda_2| > 1$$

لذا غير مستقر.

(7)

« النظائفة »

الاستقرار - Stability : تكون طريقة الفروم المركزية مستقرة :  
 إذا  $\|u^n\|_{L_2} \leq \|u^0\|_{L_2}$  عندما  $\|u^n\|_{L_2} = \left[ h \sum_{i=-\infty}^{\infty} |u_i^n|^2 \right]^{\frac{1}{2}}$

خذ استخدام تحويلات فورييه (تقطع)

$$\hat{u}(k) = h \sum_{i=-\infty}^{\infty} u_i e^{ikrh} \quad ; k \in \left[-\frac{\pi}{h}, \frac{\pi}{h}\right]$$

$$u_i = \frac{1}{2\pi} \int_{-\frac{\pi}{h}}^{\frac{\pi}{h}} \hat{u}(k) e^{ikrh} dk \quad \leftarrow$$

مطابقة بارسيبال :  $\|u\|_{L_2} = \frac{1}{\sqrt{2\pi}} \|\hat{u}\|_{L_2}$

عندما :  $\|\hat{u}\|_{L_2} = \left( \int_{-\frac{\pi}{h}}^{\frac{\pi}{h}} |\hat{u}(k)|^2 dk \right)^{\frac{1}{2}}$

إذا، أضنا بالمعادلة الظاهرة :  $u_i^{n+1} = u_i^n + r(u_{i+1}^n - 2u_i^n + u_{i-1}^n)$

وإذا أخذنا تحويل فورييه :  $h \sum_{i=-\infty}^{\infty} u_i^{n+1} e^{ikrh} = h \sum_{i=-\infty}^{\infty} u_i^n e^{ikrh} + r \left( h \sum_{i=-\infty}^{\infty} e^{ikrh} (u_{i+1}^n - 2u_i^n + u_{i-1}^n) \right)$

أي :  $\hat{u}^{n+1}(k) = \hat{u}^n(k) + r(e^{ikh} - 2 + e^{-ikh}) \hat{u}^n(k)$

$$\hat{u}^{n+1}(k) = \hat{u}^n(k) \left[ 1 - 4r \sin^2\left(\frac{k}{2}\right) \right] \quad \leftarrow$$

نعرّف  $\lambda(k) = 1 - 4r \sin^2\left(\frac{k}{2}\right)$

فيصم لدينا  $\hat{u}^{n+1} = \hat{u}^n(k) \cdot \lambda(k)$



ربما ستحتاج متطابقة لاسيفال :

$$\begin{aligned}\| \hat{U}^h \|_{\ell_2} &= \frac{1}{\sqrt{2\pi}} \| \hat{U}^h \|_{L_2} \\ &= \frac{1}{\sqrt{2\pi}} \| \lambda \hat{U}^h \|_{L_2}\end{aligned}$$

$$\| \hat{U}^h \|_{\ell_2} \leq \max_K |\lambda| \| \hat{U}^h \|_{\ell_2}$$

لذلك أهدأ:  $\max_K |\lambda(k)| \leq 1$  شرط كاف للاستقرار عملياً

$$-1 \leq 1 - 4r \sin^2 \frac{kh}{2} \leq 1$$

وتتبعه لذلك : تكون مستقر في حالة  $(r \leq \frac{1}{2})$  ...

\* إذا طبقنا نفس الطريقة على المعادلة الضمنية (مع الشغل الضمني) :

$$\hat{U}^h(k) = \lambda(k) \hat{U}^h(k)$$

$$\lambda(k) = \frac{1}{1 + 4r \sin^2 \frac{kh}{2}}$$

والاستقرار يتحقق أيما كان  $r$  (مع أجل جميع قيم  $r$ )

**Example 52. Forward Euler method**  $u_t = u_{xx} = 0$

We saw that  $T(x, t) = O(k + h^2)$ , so if  $k, h \rightarrow 0$  then  $T \rightarrow 0$ . So forward Euler is unconditionally consistent with  $u_t - u_{xx} = 0$ .

**Convergence:** Now suppose we carry out a sequence of calculations with the same initial data, but with successive mesh refinement so that  $k, h \rightarrow 0$ . We call the method convergent if, for any fixed point  $(x_*, t_*)$ ,

تقارب غير متقاربة  
دائما شروع الحد

$$x_j \rightarrow x_*, \quad t_n \rightarrow t_* \implies U_j^n \rightarrow u(x_*, t_*).$$

**Warning!** consistency  $\neq$  convergence. To get  $U_j^n$  we apply the formula successively, so the individual local truncation errors could add up.

**Example 53. Forward differences for  $u_t + u_x = 0$ , in  $t > 0, x \in \mathbb{R}$ , with initial data**

$$u(x, 0) = u_0(x) = \begin{cases} 1 & x < 0, \\ 0 & x \geq 0. \end{cases}$$

Note that the exact solution is  $u(x, t) = u_0(x - t)$  (Figure 43). Try forward differences in both derivatives:

$$\frac{U_j^{n+1} - U_j^n}{k} + \frac{U_{j+1}^n - U_j^n}{h} = 0,$$

$$\implies U_j^{n+1} = (1 + \lambda)U_j^n - \lambda U_{j+1}^n,$$

where  $\lambda = k/h$  (called the Peclet number).

Check the scheme for consistency by Taylor expanding:

$$\frac{u(x_j, t_n + k) - u(x_j, t_n)}{k} = u_t + \frac{k}{2}u_{tt} + O(k^2),$$

$$\frac{u(x_j + h, t_n) - u(x_j, t_n)}{h} = u_x + \frac{h}{2}u_{xx} + O(h^2).$$

So the local truncation error is

$$T(x, t) = O(k + h) \rightarrow 0 \text{ as } k, h \rightarrow 0.$$

so the scheme is consistent with the PDE.

Since we know the exact solution we can show that the scheme does not converge by considering  $x_* = 0, t_* > 0$ . Initially,  $U_j^0 = u_0(jh) = 0$  for all  $j \geq 0$ . But induction on  $n$  with  $U_0^{n+1} = (1 + \lambda)U_0^n - \lambda U_1^n$  for  $j \geq 0$  shows that  $U_0^{n+1} = 0$  for all  $n \geq 0$ . Since

$$u(0, (n+1)k) = u_0(-(n+1)k) = 1,$$

we see that  $U_0 \rightarrow u_0(u, h, k)$  as  $h \rightarrow 0$  with  $t_n = h n$ . If the method is consistent it does not converge.

We saw in MATLAB an example where convergence of Euler's method depended on the relative step sizes  $k$  and  $h$ .

**Example 54.** Prove that the forward Euler method for  $u_t - u_{xx} = 0$  is convergent if  $\mu = k/h^2 \leq \frac{1}{2}$ .

Let  $e_j^n = U_j^n - u(x_j, t_n)$ , sometimes called the "global truncation error".  
By definition,

$$T(x_j, t_n) = \frac{u(x_j, t_{n+1}) - u(x_j, t_n)}{k} - \frac{u(x_{j+1}, t_n) - 2u(x_j, t_n) + u(x_{j-1}, t_n))}{h^2}$$

$$\Rightarrow u(x_j, t_{n+1}) = kT(x_j, t_n) + u(x_j, t_n) + \mu(u(x_{j+1}, t_n) - 2u(x_j, t_n) + u(x_{j-1}, t_n)).$$

So

$$\begin{aligned} |e_j^{n+1}| &= |U_j^{n+1} - u(x_j, t_{n+1})| \\ &= |U_j^n + \mu(U_{j+1}^n - 2U_j^n + U_{j-1}^n) - kT(x_j, t_n) - u(x_j, t_n) \\ &\quad + \mu(u(x_{j+1}, t_n) - 2u(x_j, t_n) + u(x_{j-1}, t_n))| \\ &= |(1 - 2\mu)(U_j^n - u(x_j, t_n)) + \mu(U_{j+1}^n - u(x_{j+1}, t_n)) \\ &\quad + \mu(U_{j-1}^n - u(x_{j-1}, t_n)) - kT(x_j, t_n)| \\ &\leq |1 - 2\mu| \cdot |e_j^n| + \mu|e_{j+1}^n| + \mu|e_{j-1}^n| + k|T(x_j, t_n)|, \end{aligned}$$

where we used the triangle inequality.

If  $\mu \leq \frac{1}{2}$  then  $|1 - 2\mu| = 1 - 2\mu$ , so

$$|e_j^{n+1}| \leq \max_i |e_i^n| + kM\left(\frac{1}{2} + \frac{k^2}{12}\right) = \max_i |e_i^n| + \frac{k^2}{2}M\left(1 + \frac{1}{6\mu}\right).$$

Now use induction. We have  $e_j^0 = 0$ , so

$$|e_j^1| \leq \frac{k^2}{2}M\left(1 + \frac{1}{6\mu}\right).$$

$$|e_j^2| \leq 2\frac{k^2}{2}M\left(1 + \frac{1}{6\mu}\right),$$

:

$$|e_j^n| \leq n\frac{k^2}{2}M\left(1 + \frac{1}{6\mu}\right) = \frac{k^2}{2}t_n M\left(1 + \frac{1}{6\mu}\right).$$

So  $|e_j^n| \rightarrow 0$  as  $k \rightarrow 0$  for all  $j$ . Hence the method is convergent when  $\mu \leq \frac{1}{2}$ .

\* Note that case  $\mu > \frac{1}{2}$ .

since  $u_t = -au_x$  and  $u_{tt} = -au_{xt} = -a \frac{\partial}{\partial x} u_t = a^2 u_{xx}$ .

The von Neumann stability analysis. The growth factor of Lax-Wendroff scheme is

$$\begin{aligned} g(\theta) &= 1 - \frac{\mu}{2} (e^{i\theta} - e^{-i\theta}) + \frac{\mu^2}{2} (e^{-i\theta} - 2 + e^{i\theta}) \\ &= 1 - \mu i \sin \theta - 2\mu^2 \sin^2(\theta/2), \end{aligned}$$

where again  $\theta = h\xi$ . Therefore we proceed with the following derivation

$$\begin{aligned} |g(\theta)|^2 &= \left(1 - 2\mu^2 \sin^2 \frac{\theta}{2}\right)^2 + \mu^2 \sin^2 \theta \\ &= 1 - 4\mu^2 \sin^2 \frac{\theta}{2} + 4\mu^4 \sin^4 \frac{\theta}{2} + 4\mu^2 \sin^2 \frac{\theta}{2} \left(1 - \sin^2 \frac{\theta}{2}\right) \\ &= 1 - 4\mu^2 (1 - \mu^2) \sin^4 \frac{\theta}{2} \\ &\leq 1 - 4\mu^2 (1 - \mu^2). \end{aligned}$$

We conclude that  $|g(\theta)| \leq 1$  if  $\mu \leq 1$ , that is  $\Delta t \leq h/|a|$ . If  $\Delta t > h/|a|$ , there are  $\xi$ 's such that  $|g(\theta)| > 1$  and the scheme is unstable.

Lax-Wendroff scheme is second order accurate both in time and space. To show this, we investigate the local truncation error:

$$\begin{aligned} T(x, t) &= \frac{u(x, t + \Delta t) - u(x, t)}{\Delta t} - \frac{a(u(x + h, t) - u(x - h, t))}{2h} \\ &\quad - \frac{a^2 \Delta t (u(x - h, t) - 2u(x, t) + u(x + h, t))}{2h^2} \\ &= u_t + \frac{\Delta t}{2} a u_{xx} - \frac{a^2 \Delta t}{2} u_{xx} + O((\Delta t)^2 + h^2) \\ &= O((\Delta t)^2 + h^2) \end{aligned}$$

9.11.1 A finite difference method (CT-CT) for the second order wave equation.

$$\frac{U_j^{k+1} - 2U_j^k + U_j^{k-1}}{(\Delta t)^2} = a^2 \frac{U_{j-1}^k - 2U_j^k + U_{j+1}^k}{h^2} \quad (9.23)$$

The method is second order accurate both in time and space  $((\Delta t)^2 + h^2)$ . The CFL constraints of this method is  $\Delta t \leq \frac{h}{|a|}$  this will be verified through the following discussion.

The von Neumann analysis gives:

$$\frac{g - 2 + 1/g}{(\Delta t)^2} = a^2 \frac{e^{-i h \xi} - 2 + e^{i h \xi}}{h^2}$$

Let  $\mu = \frac{|a| \Delta t}{h}$ . The equation above becomes:

$$g^2 - 2g + 1 = \mu^2 (-4 \sin^2 \theta) g,$$

or

$$g^2 - 2(1 - 4\mu^2 \sin^2 \theta)g + 1 = 0,$$

where  $\theta = h\xi/2$ . Solve the equation above to get

$$g = 1 - 2\mu^2 \sin^2 \theta \pm \sqrt{(1 - 2\mu^2 \sin^2 \theta)^2 - 1}.$$

Note that  $1 - 2\mu^2 \sin^2 \theta \leq 1$ . If we also have  $1 - 2\mu^2 \sin^2 \theta < -1$ , then for one of roots

$$g_1 = 1 - 2\mu^2 \sin^2 \theta - \sqrt{(1 - 2\mu^2 \sin^2 \theta)^2 - 1} < -1,$$

or  $|g_1| > 1$  for some  $\theta$ , thus the scheme is unstable.

In order to have a stable scheme, we should require that  $1 - 2\mu^2 \sin^2 \theta \geq -1$ , or  $\mu^2 \sin^2 \theta \leq 1$ . This can be guaranteed if  $\mu^2 \leq 1$  or  $\Delta t \leq h/|a|$ . This is the CFL condition that we have expected. Under this CFL constraints, we would have

$$|g|^2 = (1 - 2\mu^2 \sin^2 \theta)^2 + (1 - (1 - 2\mu^2 \sin^2 \theta)^2) = 1,$$

since the second part in the expression of  $g$  is imaginary. Thus the scheme is neutrally stable.

### Finite Differencing of Hyperbolic PDE's

Consider a simple example of a hyperbolic partial differential (or wave) equation with one spatial independent variable

$$u^2 \frac{\partial^2 \Phi}{\partial x^2} = \frac{\partial^2 \Phi}{\partial t^2} \quad (23)$$

where  $u$  is the speed of the wave. The equivalent finite difference approximation is

$$u^2 \frac{\Phi(i-1, j) - 2\Phi(i, j) + \Phi(i+1, j)}{(\Delta x)^2} = \frac{\Phi(i, j+1) - 2\Phi(i, j) + \Phi(i, j-1)}{(\Delta t)^2} \quad (24)$$

where  $x = i\Delta x$ ,  $i = 1, 2, 3, \dots, n$ ,  $t = j\Delta t$ ,  $j = 1, 2, \dots$ . In (24), we use the central difference

$$= \left( \frac{u\Delta t}{\Delta x} \right)^2 \quad (25)$$

$$\Phi(i, j+1) = (1-r)\Phi(i, j) + r[\Phi(i+1, j) + \Phi(i-1, j) - \Phi(i, j-1)] \quad (26)$$

$$\Phi(i, j+1) = \Phi(i+1, j) + \Phi(i-1, j) - \Phi(i, j-1) \quad (27)$$

We assume a trial solution of the form

$$\Phi_i^n = A^n e^{jkix} \quad (28)$$

Substituting this into Eq. (26) results in

$$A^{n+1} e^{jkix} = 2(1-r)A^n e^{jkix} + r(e^{jkx} + e^{-jkx})A^n e^{jkix} - A^{n-1} e^{jkix} \quad (29)$$

or

$$A^{n+1} = A^n [2(1-r) + 2r \cos kx] - A^{n-1} \quad (30)$$

In terms of  $g = A^{n+1}/A^n$ , Eq. (30) becomes

$$g^2 - 2pg + 1 = 0 \quad (31)$$

where  $p = 1 - 2r \sin^2 \frac{kx}{2}$ . The quadratic equation (31) has solutions

$$g_1 = p + [p^2 - 1]^{1/2}, \quad g_2 = p - [p^2 - 1]^{1/2}.$$

For  $|g_i| \leq 1$ , where  $i = 1, 2$ ,  $p$  must lie between 1 and -1, i.e.,  $-1 \leq p \leq 1$  or

$$-1 \leq 1 - 2r \sin^2 \frac{kx}{2} \leq 1 \quad (32)$$

which implies that  $r \leq 1$  or  $u\Delta t \leq \Delta x$  for stability. This idea can be extended to show that the stability condition for two-dimensional wave equation is  $u\Delta t/h < \frac{1}{\sqrt{2}}$ , where  $h = \Delta x = \Delta y$ .

### Simplification of von Neumann stability analysis for one step time marching method.

Assume that we have a one step time marching method  $U^{k+1} = f(U^k, U^{k+1})$ . We have the following theorem that tells the stability of a finite difference method.

**Theorem 8.2** Let  $\theta = h\xi$ . A one-step finite difference scheme (with constant coefficients) is stable if and only if there is a constant  $K$  (independent of  $\theta$ ,  $\Delta t$ , and  $h$ ) and some positive grid spacing  $\Delta t_0$  and  $h_0$  such that

$$|g(\theta, \Delta t, h)| \leq 1 + K\Delta t \quad (8.28)$$

for all  $\theta$ ,  $0 < k \leq k_0$ , and  $0 < h \leq h_0$ . If  $g(\theta, \Delta t, h)$  is independent of  $h$  and  $\Delta t$ , the stability condition (8.28) can be replaced with

$$|g(\theta)| \leq 1. \quad (8.29)$$

This theorem shows that to determine the stability of a finite difference scheme we need consider only the amplification factor  $g(h\xi) = g(\theta)$ . This observation is due to von Neumann, and because of that, this analysis is usually called von Neumann analysis. We present some examples below.

We can follow the following steps for the von Neumann analysis:

1. Set  $U_j^k = e^{i j h \xi}$ . Plugging the expression into the finite difference scheme.
2. Express  $U_j^{k+1}$  as  $U_j^{k+1} = g(\xi) e^{i j h \xi}$ .
3. Solve  $g(\xi)$  and determine whether or when  $|g(\xi)| \leq 1$  for the stability.

#### Example 2.

The stability of backward Euler's method for the heat equation  $u_t = \beta u_{xx}$  is:

$$U_i^{k+1} = U_i^k + \mu (U_{i-1}^{k+1} - 2U_i^{k+1} + U_{i+1}^{k+1}), \quad \mu = \frac{\beta \Delta t}{h^2}.$$

Follow the procedure mentioned above, we have

$$\begin{aligned} g(\xi) e^{i j h \xi} &= e^{i j h \xi} + \mu (e^{i(j-1)h\xi} - 2e^{i j h \xi} + e^{i(j+1)h\xi}) g(\xi) \\ &= e^{i j h \xi} (1 + \mu (e^{-i h \xi} - 2 + e^{i h \xi})) g(\xi). \end{aligned}$$

We solve  $g(\xi)$  to get

$$\begin{aligned} g(\xi) &= \frac{1}{1 - \mu (e^{-i h \xi} - 2 + e^{i h \xi})} \\ &= \frac{1}{1 - \mu (2 \cos(h\xi) - 2)} = \frac{1}{1 + 4\mu \sin^2(h\xi)/2} < 1 \end{aligned}$$